**Gesture Recognition Case study**

Below is the list of experiments conducted with 3 kinds of models and their outcomes. We have taken steps to enhance the model at each step. The decisions are based on some additional intermediatory steps that have not been listed in the document.

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| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | **Model** | **Configuration** | **Number of Parameters** | **Training Loss** | **Training Accuracy** | **Validation Loss** | **Validation**  **Accuracy** | **Observations** | **Decision** |
|  | CNN+LSTM | Epochs = 10,  Feature map = [8, 16, 32, 64, 128]  Dense = [1000,500,5]  Batch size = 10  Epochs = 10  Learning rate patience = 5 | 3,974,609 | 1.1772 | 58.21% | 1.6759 | 38% | The model starts overfitting after a few models | We will increase the data through augmentation. |
|  | CNN+LSTM | Epochs = 10,  Feature map = [8, 16, 32, 64, 128]  Dense = [1000,500,5]  Batch size = 10  Epochs = 10  Learning rate patience = 5 | 3,974,609 | 1.6063 | 27.54% | 1.6405 | 19.17% | We see the accuracy is poor and loss is high. | We add batch normalization Layers after convolutions. |
|  | CNN+LSTM | Epochs = 10,  Feature map = [8, 16, 32, 64, 128]  Dense = [1000,500,5]  Batch size = 10  Epochs = 20  Learning rate patience = 5  Add Batch Normalizations | 3,974,705 | 1.6027 | 26.57% | 1.4743 | 37.50% | Slight improvement but the model is still not performing well. | We will reduce the dense layer neurons to original 256,128 |
|  | CNN+LSTM | Epochs = 10,  Feature map = [8, 16, 32, 64, 128]  Dense = [256,128,5]  Layer = 4  Batch size = 10  Epochs = 10  Learning rate patience = 5 | 982,613 | 1.2777 | 45.41% | 1.1535 | 57% | Model Stopped Learning after a few iterations. There was no improvement in loss. | We will try to increase the learning rate. In fact reduce the learning patience. |
|  | CNN+LSTM | Epochs = 10,  Feature map = [8, 16, 32, 64, 128]  Dense = [256,128,5]  Batch size = 10  Epochs = 10  Learning rate patience = 2 | 982,709 | 0.7258 | 70.98% | 0.8363 | 67% | This is a significant improvement in model performance. | We will now experiment with the GRU model. |
| **CNN+GRU** | | | | | | | | | |
|  | CNN+GRU | Epochs = 10  Feature map = [8, 16, 32, 64, 128, 256]  Dense = [1000,500,5]  Layer = 5  Batch size = 10  Epochs = 10  Optimizer Adam | 1,943,345 | 1.2311 | 47.83% | 0.9083 | 62.50% | Training and validation losses are high, but the model performs a decent job. | Maybe the dropouts are cancelling more layers than required. We try removing dropout layers |
|  | CNN+GRU | Epochs = 10  Feature map = [8, 16, 32, 64, 128, 256]  Dense = [1000,500,5]  Layer = 5  Batch size = 10  Epochs = 10  Optimizer Adam | 1,943,345 | 0.5730 | 81.59% | 0.8050 | 69.67% | Model performance has improved significantly on training data after removing dropout layers, but validation accuracy has only improved slightly | We can try decreasing image size to 84X84, increasing epochs |
|  | CNN+GRU | Epochs = 10  Feature map = [8, 16, 32, 64, 128, 256]  Dense = [1000,500,5]  Layer = 5  Batch size = 10  Epochs = 20  Optimizer Adam | 1,303,345 | 0.5008 | 83.58% | 0.6299 | 74.33% | Model performance has increased significantly after reducing the image size. | We try adding one additional dense layer for better classification |
|  | CNN+GRU | Epochs = 10  Feature map = [8, 16, 32, 64, 128, 256]  Dense = [1000, 500, 250, 5]  Layer = 5  Batch size = 10  Epochs = 20  Optimizer Adam | 1,303,345 | 0.9942 | 66.5% | 0.9089 | 67.33% | The model performance has reduced significantly, and the losses have increased | We try reducing the learning patience |
|  | CNN+GRU | Epochs = 10  Feature map = [8, 16, 32, 64, 128, 256]  Dense = [1000, 500, 5]  Layer = 5  Batch size = 10  Epochs = 20  Optimizer Adam | 1,972,595 | 0.6762 | 76.95% | 0.8439 | 66.5% | The performance has still not improved after reducing the learning patience. | We can try building model using Conv3D |
| **CONV 3D** | | | | | | | | | |
|  | Conv3D | Feature map = [8,16,32,64]  Dense = [256, 128, 5]  Kernel = (3, 3, 3)  Layers = 4  Batch size = 10  Epochs = 10  Optimizer - SGD | 863,989 | 1.1530 | 54.02% | 0.9234 | 56% | The model performs with low accuracy. | We try increasing number of epochs and changing optimizer |
|  | Conv3D | Feature map = [8, 16, 32, 64]  Dense = [256, 128, 5]  Kernel = (3, 3, 3)  Layers = 4  Batch size = 10  Epochs = 20  Optimizer - Adam | 863,989 | 0.6139 | 77.11% | 0.6639 | 73% | The model performance has improved significantly. The loss has reduced, and accuracy has increased. | We try adding more perceptron in the dense layer |
|  | Conv3D | Feature map = [8, 16, 32, 64]  Dense = [1000, 500, 5]  Kernel = (3, 3, 3)  Layers = 4  Batch size = 10  Epochs = 20  Optimizer - Adam | 3,667,381 | 0.3780 | 85.07% | 0.5135 | 81% | The model performance has again improved significantly. Training loss is much less, and accuracy has improved quite significantly | We try adding one more layer with dropout |
|  | Conv3D | Feature map = [8, 16, 32, 64, 128]  Dense = [1000, 500, 5]  Kernel = (3, 3, 3)  Layers = 5  Batch size = 10  Epochs = 20  Optimizer - Adam | 6,877,237 | 0.4495 | 82.09% | 0.4586 | 80% | The model has performed somewhat similarly to the previous model. There is no significant loss of gain in accuracy. | We try adding one more layer with Batch normalization |
|  | Conv3D | Feature = [8, 16, 32, 64, 128, 256]  Dense = [1000, 500, 5]  Kernel = (3, 3, 3)  Layers = 6  Batch size = 10  Epochs = 20  Optimizer - Adam | 13,444,533 | 0.4912 | 79.60% | 0.5731 | 79% | The model has performed poorly as compared to previous 2 models. The loss has increased, and accuracy has dropped. | We will try to reduce the filter size for looking at the efficiency. |
|  | Conv3D | Feature = [8, 16, 32, 64, 128, 256]  Dense = [1000, 500, 5]  Kernel = (3, 3, 3)  Layers = 6  Batch size = 10  Epochs = 20  Optimizer - Adam | 13,441,645 | 1.0849 | 57.49% | 0.9909 | 55% | The accuracy decreased significantly. | We try training a new model using transfer learning |